

**Number Sets.** An expression such as  $k \in \mathbb{N}$  (read as “ $k$  is an element of  $\mathbb{N}$ ” or “ $k$  in  $\mathbb{N}$ ”) means that  $k$  is a natural number; a **natnum**.

$\mathbb{N}$  = natural numbers =  $\{0, 1, 2, \dots\}$ .

$\mathbb{Z}$  = integers =  $\{\dots, -2, -1, 0, 1, \dots\}$ . For the set  $\{1, 2, 3, \dots\}$  of positive integers, the **posints**, use  $\mathbb{Z}_+$ . Use  $\mathbb{Z}_-$  for the negative integers, the **negints**.

$\mathbb{Q}$  = rational numbers =  $\{\frac{p}{q} \mid p \in \mathbb{Z} \text{ and } q \in \mathbb{Z}_+\}$ . Use  $\mathbb{Q}_+$  for the positive **ratnums** and  $\mathbb{Q}_-$  for the negative ratnums.

$\mathbb{R}$  = reals. The **posreals**  $\mathbb{R}_+$  and the **negreals**  $\mathbb{R}_-$ .

$\mathbb{C}$  = complex numbers, also called the **complexes**.

An “**interval of integers**”  $[b .. c]$  means the intersection  $[b, c] \cap \mathbb{Z}$ ; ditto for open and closed intervals. So  $[e .. 2\pi] = \{3, 4, 5, 6\} = [3 .. 6] = (2 .. 6]$ . We allow  $b$  and  $c$  to be  $\pm\infty$ ; so  $(-\infty .. -1]$  is  $\mathbb{Z}_-$ .

**Mathematical objects.** Seq: ‘sequence’. poly(s): ‘polynomial(s)’. irred: ‘irreducible’. Coeff: ‘coefficient’ and var(s): ‘variable(s)’ and parm(s): ‘parameter(s)’. Expr.: ‘expression’. Col: ‘Constant of Integration’. Lol: ‘Limit(s) of Integration’.

Fnc: ‘function’ (so ratfnc: means rational function, a ratio of polynomials). cty: ‘continuity’. cts: ‘continuous’. diff’able: ‘differentiable’.

Soln: ‘Solution’. Thm: ‘Theorem’. Prop’n: ‘Proposition’. CEX: ‘Counterexample’. eqn: ‘equation’. RhS: ‘RightHand Side’ of an eqn or inequality. LhS: ‘lefthand side’. Sqrt or Sqroot: ‘square-root’, e.g., “the sqroot of 16 is 4”. Ptn: ‘partition’, but pt: ‘point’, as in “a fixed-pt of a map”.

FTC: ‘Fund. Thm of Calculus’. IVT: ‘intermediate-Value Thm’. MVT: ‘Mean-Value Thm’. CoV: ‘Change-of-Variable’.

**Phrases.** WLOG: ‘Without loss of generality’. TFAE: ‘The following are equivalent’. ITOf: ‘In Terms Of’. OTForm: ‘of the form’. FTSOC: ‘For the sake of contradiction’. Use iff: ‘if and only if’.

IST: ‘It Suffices to’ as in ISTShow, ISTExhibit.

Use w.r.t: ‘with respect to’ and s.t: ‘such that’.

**Latin:** e.g: *exempli gratia*, ‘for example’. i.e: *id est*, ‘that is’. QED: *quod erat demonstrandum*, meaning “end of proof”.

## LinA quizzes so far...

**Q0:** Mon.  
31,Aug The **slope** of line  $3[y - 5] = 2[x - 2]$  is  $\underline{\dots}$ .

Point  $(-4, y)$  lies on this line, where  $y = \underline{\dots}$ .

Let  $y = f(x) := [5 + \sqrt[3]{x}]/2$ . Its inverse-function is  $f^{-1}(y) = \underline{\dots}$ .

**Q1:** Wed.  
09 Sep **Henceforth**, let **AT** mean “Always True”, **AF** mean “Always False” and **Nei** mean “Neither always true nor always false”. Below,  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  repr. *distinct*, non-zero vectors in  $\mathbb{R}^4$ , a  $\mathbb{R}$ -VS. Please  the correct response:

**y1** If  $\mathbf{w} \in \text{Span}\{\mathbf{u}, \mathbf{v}\}$  then  $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$  is linearly independent. **AT AF Nei**

**y2** If  $\mathbf{w} \notin \text{Span}\{\mathbf{u}, \mathbf{v}\}$  then  $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$  is linearly independent. **AT AF Nei**

**y3** Collection  $\{\mathbf{0}, \mathbf{w}\}$  is linearly-indep. **AT AF Nei**

**y4**  $\text{Span}\{\mathbf{u}, \mathbf{v}, \mathbf{w}, \mathbf{u} + 2\mathbf{v} + 3\mathbf{w}\}$  is all of  $\mathbb{R}^4$ . **AT AF Nei**

**y5** If none of  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  is a multiple of the other vectors, then  $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$  is linearly independent. **AT AF Nei**

**Q2:** Fri.  
18 Sep A system of 3 linear equations in unknowns  $x_1, \dots, x_5$  reduces to the augmented matrix

$$\left[ \begin{array}{ccccc|c} 1 & 1 & 0 & 0 & 1 & 12 \\ 0 & 0 & 1 & 0 & -8 & 34 \\ 0 & 0 & 0 & 1 & 5 & -56 \end{array} \right]$$
 which is in RREF. Please  each pivot entry.

OYOP, describe the general solution in this form,

$$\left[ \begin{array}{c} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{array} \right] = \left[ \begin{array}{c} ? \\ ? \\ ? \\ ? \\ ? \end{array} \right] + \alpha \left[ \begin{array}{c} ? \\ ? \\ ? \\ ? \\ ? \end{array} \right] + \beta \left[ \begin{array}{c} ? \\ ? \\ ? \\ ? \\ ? \end{array} \right] + \gamma \left[ \begin{array}{c} ? \\ ? \\ ? \\ ? \\ ? \end{array} \right] + \dots$$

where each  $\alpha, \beta, \gamma, \delta, \dots$  is a free variable (either  $x_1$  or... or  $x_5$ ), and each column vector has specific numbers in it.  $\text{Dim}(\text{SolnFlat}) = \underline{\dots}$ .

**Q3:** Wed.  
30 Sep Inverse of  $\begin{bmatrix} 3 & 1 & 0 \\ 5 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$  is

$$\begin{bmatrix} \underline{\dots} & \underline{\dots} & \underline{\dots} \\ \underline{\dots} & \underline{\dots} & \underline{\dots} \\ \underline{\dots} & \underline{\dots} & \underline{\dots} \end{bmatrix}.$$

**Q4:** Mon. 05Oct Let  $R_\theta$  be the std. rotation [by  $\theta$ ] matrix. With

$$C := \begin{bmatrix} \sqrt{3} & -1 \\ 1 & \sqrt{3} \end{bmatrix} \quad \text{and} \quad B := \begin{bmatrix} \sqrt{2} & -\sqrt{2} \\ \sqrt{2} & \sqrt{2} \end{bmatrix},$$

the product  $[CB]^{22} = \alpha \cdot R_\theta$ , with  $\alpha = \dots \in \mathbb{R}_+$  and  $\theta = \dots \in (-180^\circ, 180^\circ]$ . [Hint: Don't multiply matrices. Geometrically,  $C$  and  $B$  represent what linear-trns?]

**Q5:** Tue. 06Oct Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  rotate the plane CCW by  $60^\circ$ , then vertically stretch by a factor of 5. W.r.t the std basis,

$$[\![T]\!]_{\mathcal{E}}^{\mathcal{E}} = \begin{bmatrix} & & & \\ & \text{---} & | & \text{---} \\ & & & \end{bmatrix}.$$

**Q6:** Tue. 20Oct Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) := \begin{bmatrix} 3x - y \\ 2x + 6y \end{bmatrix}$ . W.r.t ordered-basis  $B := \left(\begin{bmatrix} 5 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \end{bmatrix}\right)$ , let  $M := [\![T]\!]_B^B$ . Then  $M = RTR^{-1}$ ,

$$\text{where } R = \begin{bmatrix} & & & \\ & \text{---} & | & \text{---} \\ & & & \end{bmatrix}, \quad M = \begin{bmatrix} & & & \\ & \text{---} & | & \text{---} \\ & & & \end{bmatrix}.$$

**Q7:** Tue. 20Oct In  $\mathbb{R}^3$ , the closest point to  $v := (1, 2, 3)$  on the line through  $\mathbf{0}$  and  $q := (-2, 7, 0)$ , is  $\alpha q$ , where  $\alpha = \dots$

In  $\mathbb{R}^2$ , with  $s := (1, 8)$  and  $w := (4, -2)$ , compute  $\text{Orth}_w(s) = \dots$

**Q8:** Mon. 30Nov Let  $B := \begin{bmatrix} 1 & 2 & 1 & 0 & 1 \\ 3 & 6 & 0 & -3 & 0 \end{bmatrix}$ . Then  $R := \text{RREF}(B)$  is [show no work, here]

$$R = \left[ \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right].$$

**I** For subspace  $V := \text{Nul}(L_B)$ , use back-substitution, and *scaling*, to produce an integer basis

$$v_1 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right), \quad v_2 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right),$$

$$v_3 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right), \quad v_4 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right).$$

[Note: Only use as many as the dimension of  $V$ .]

II

Apply Gram-Schmidt to compute an **orthogonal integer-basis** for  $V$ :

$$b_1 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right), \quad b_2 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right),$$

$$b_3 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right), \quad b_4 := \left( \begin{array}{c|c|c|c|c} & & & & \\ \hline & & & & \\ \hline \end{array} \right).$$

[Entries are integers]

Arrange that the Gcd of the entries in each vector is 1, and that the first non-zero value is positive.

**Q9:** Tue. 08Dec Line  $y = [\dots]x + \dots$  is the least-squares best-fit to data pts  $\{(-2, 0), (-1, 0), (1, 0), (2, 1)\}$ .

*That's All, Folks!*