

For questions A1 and A2 please show no work. Please write **DNE** in a blank if the described object does not exist or if the indicated operation cannot be performed.

Do **not** approx.: If your result is “ $\sin(\sqrt{\pi})$ ” then write that rather than .9797….

**A1:** Let  $A := \begin{bmatrix} 2 & 3 & 4 \\ -1 & -1 & 1 \\ -2 & 0 & 1 \end{bmatrix}$ ,  $B := \begin{bmatrix} \sqrt{2} & 0 & \sqrt{2} \\ 0 & -1 & 5 \end{bmatrix}$ , and let  $\mathbf{u} := \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ ,  $\mathbf{w} := \begin{bmatrix} 1 \\ \frac{1}{2} \\ -1 \end{bmatrix}$ .

**a** So  $AB = \dots$ ,  $BA = \dots$ .

**b** Circle those of the following vectors which are in  $\text{Span}\{\mathbf{u}, \mathbf{w}\}$ .

$$\mathbf{v}_1 := (2, 4, 6) \quad \mathbf{v}_2 := (2, 4, -6) \quad \mathbf{v}_3 := (0, 0, 0).$$

For the next two parts, let **AT** mean “Always True”, let **AF** mean “Always False”, let **Nei** mean “NEither always true nor always false”. Please **circle** the correct response. Below,  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  represent *non-zero* vectors in  $\mathbb{R}^4$ .

**c** If  $\mathbf{w} \in \text{Span}\{\mathbf{u}, \mathbf{v}\}$  then  $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$  is linearly independent. **AT AF Nei**

If  $\mathbf{w} \notin \text{Span}\{\mathbf{u}, \mathbf{v}\}$  then  $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$  is linearly independent. **AT AF Nei**

**d**  $\text{Span}\{\mathbf{u}, \mathbf{v}, \mathbf{w}, \mathbf{u} + 2\mathbf{v} + 3\mathbf{w}\}$  is all of  $\mathbb{R}^4$ . **AT AF Nei**

If none of  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  is a multiple of the other vectors, then  $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$  is lin. independent. **AT AF Nei**

**a** The inverse of  $\begin{bmatrix} 1 & -6 & -7 \\ -3 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$  is

**f** Give an example of two  $2 \times 2$  matrices  $A \neq B$  for which  $A^2 = B^2$ .  $A = \dots$  and  $B = \dots$ .

**g** Suppose  $T$  is a linear map from  $\mathbb{R}^3$  to  $\mathbb{R}^2$ . Let  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$  be the standard basis for  $\mathbb{R}^3$ , and let  $\{\mathbf{v}_1, \mathbf{v}_2\}$  be the standard basis for  $\mathbb{R}^2$ . Suppose that  $T(\mathbf{e}_1) = \mathbf{v}_1 - 2\mathbf{v}_2$  and  $T(\mathbf{e}_2) = 4\mathbf{v}_2$  and  $T(\mathbf{e}_3) = 5\mathbf{v}_1 - 3\mathbf{v}_2$ . Then the matrix of  $T$  is:  $\dots$

**h,i** Consider these two matrices:

$$R := \begin{bmatrix} \sqrt{3}/2 & -1/2 \\ 1/2 & \sqrt{3}/2 \end{bmatrix} \quad \text{and} \quad A := \begin{bmatrix} \sqrt{2}/2 & -\sqrt{2}/2 \\ \sqrt{2}/2 & \sqrt{2}/2 \end{bmatrix}.$$

Determine the matrix  $[RA]^{36} = \dots$ .

[Hint: You don't need multiply matrices. Think of the linear transformations that these matrices represent.]

**A2:** Let  $\mathbf{v}$  be the unit vector in direction  $\mathbf{e}_3 + \mathbf{e}_2$  (on the sphere, halfway between  $\hat{\mathbf{k}}$  and  $\hat{\mathbf{j}}$ ). Let  $R$  be the transformation which rotates CCW about  $\mathbf{v}$  by 90 degrees. Then  $R(\mathbf{e}_1) = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$  where

$$x = \dots, y = \dots, z = \dots.$$

**A3:** A system of 3 equations in unknowns  $x_1, \dots, x_5$  reduces to the augmented matrix  $\begin{bmatrix} 1 & 6 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 8 & 0 \\ 0 & 0 & 0 & 1 & 5 & 0 \end{bmatrix}$ . On your own paper, describe the *general solution* in this form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \alpha \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \beta \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \gamma \begin{bmatrix} ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix} + \dots$$

where each  $\alpha, \beta, \gamma, \delta, \dots$  is a free variable (either  $x_1$  or... or  $x_5$ ), and each column vector has specific numbers in it. The *number of free variables* is  $\dots$ .

**A1:**  180pts

**A2:**  45pts

**A3:**  55pts

**Total:**  280pts

Please PRINT your **name** and **ordinal**. Ta:

Ord:

**HONOR CODE:** “I have neither requested nor received help on this exam other than from my professor.”

Signature: